

# WPI PPL System Development Updates & Overview of the results from the August 2008 WPI PIPILTER Workshop

---

David Cyganski, James Duckworth

Electrical and Computer Engineering Department  
*Worcester Polytechnic Institute*  
*Worcester, Massachusetts*

*PIPILTER Workshop August 3-4, 2009*



# 2008 PPL Workshop Demo Day

## WFD: Full CONOPs search and rescue



Five WFD teams  
test five search  
and rescue systems



# PIPLTER Workshop '08: Demo Day

---

- Demo Day hosted by the WPI Workshop team and the Worcester Fire Department.
- Purpose: Test PPL and Homing technology in the context of simulated “real world” fire service operations so that:
  - Firefighters can assess/understand current technological capabilities
  - Provide feedback to the technologists so that products ultimately developed meet the needs of first responders.

# Construction of Test Plan

---

- The detailed planning for this exercise started many weeks before the Wednesday event
  - Plans assembled and reviewed by WPI workshop team, WFD and CTC.
- The standard operating procedures and policies of the Worcester Fire Department were used as the foundation of the scenario, so that it would closely match the real world needs.

# Test Site

- WPI campus building, Atwater Kent, was selected for its availability and a certain degree of challenge due to its layout and steel/concrete structure.



Entrance to 130x75 ft<sup>2</sup>  
wing used in test

# Scenario

---

- A fire attack team entered the building;
- As conditions worsened, the team was forced to evacuate.
- When personnel were accounted for, it was found that one person was missing.
- Using the various location systems, an RIT attempts to locate the victim for safe removal

A new group of WFD volunteers were used as the attack team and rescue team on each system trial

# Locator Tests

---

- The first two tests were conducted with locator systems, using diverse technologies
  - WPI: RF location
  - Rex Systems Inc./ENSCO: Inertial navigation
- Command console (with screen projection) displayed location of firefighters on building plan.
- WPD incident commander radioed directions over the normal department two way radios.
- Search team was told of hazards, distances, directions to travel and to climb stairs as their locations were tracked by the commander.

# Locator Tests

- Training Chief and the Chief in charge of Incident Command provide the firefighters with a briefing of what was expected of each task team.
- Repeated for each system under test





# Outfitting the firefighters

- The firefighters usual Personnel Protective Equipment was augmented with locator and possibly bio-monitoring technologies (as with WPI system) that included the locator transmitter, its associated antenna, as well as bio sensors.
- Note headband with WPI pulse oximeter
- Not visible is Foster Miller T-shirt with bio-sensors which was part of WPI system.



# Command Center

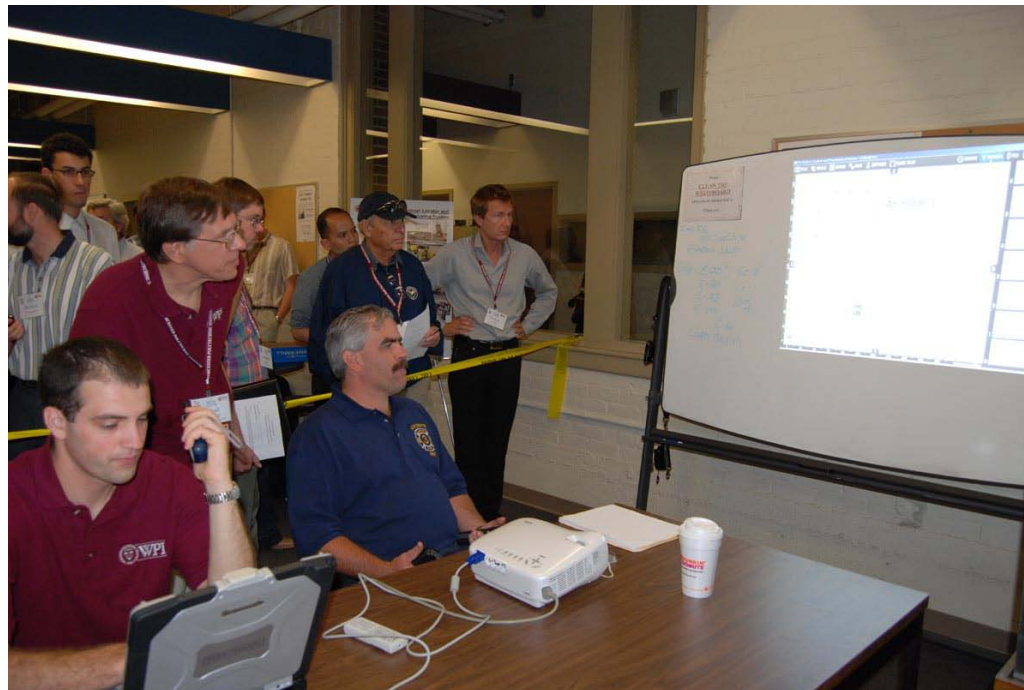
---

- Locator technologists provided support for the incident commander.



# Command Display

- Commander monitored progress of the attack team on the locator display.
- The location of each firefighter was shown along with their bio-status if supported.



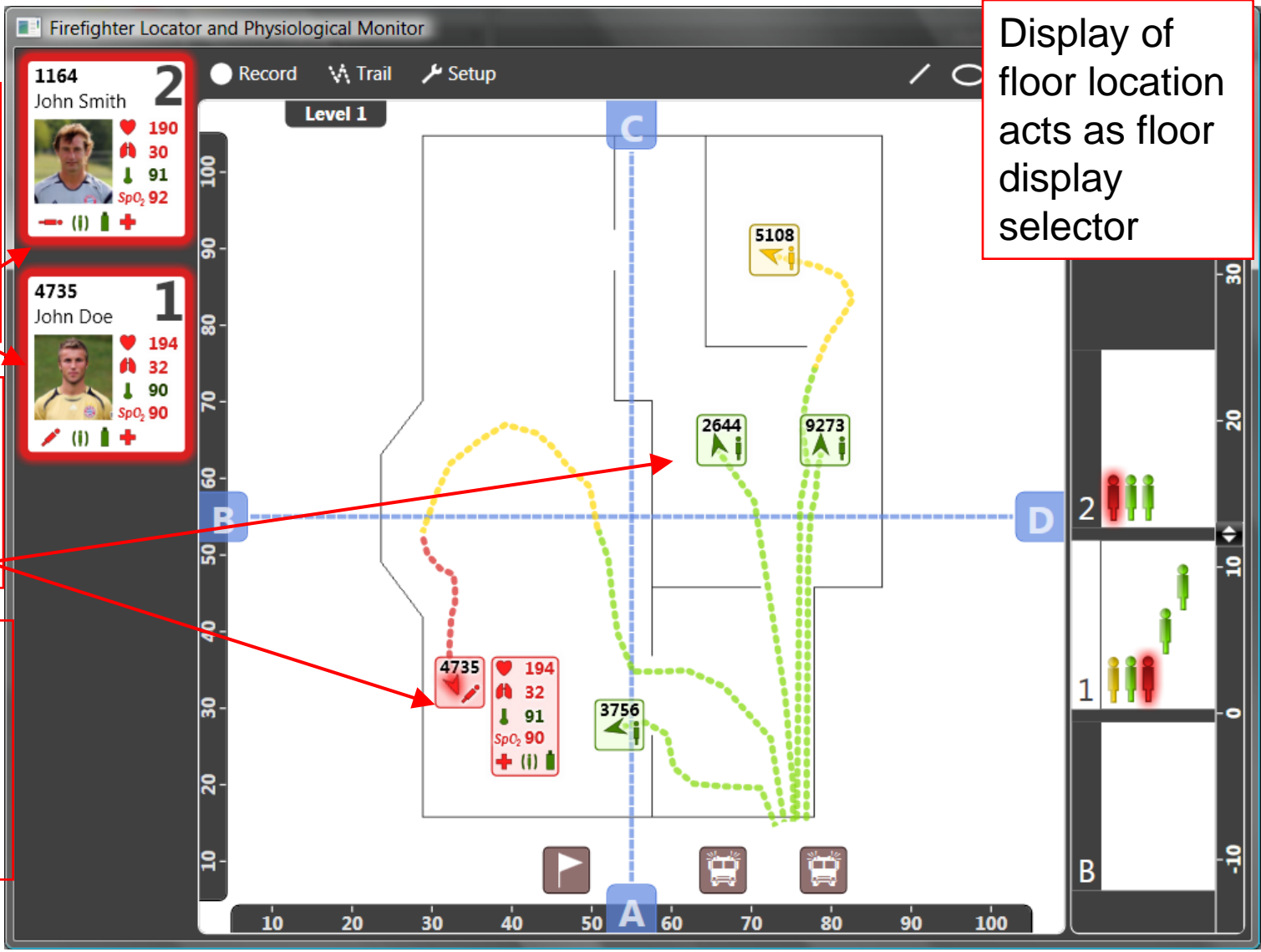
# WPI/FMI Locator/Health Status Display

Info pop-ups for all firefighters in physiological distress

Icons indicate location, direction and ID code

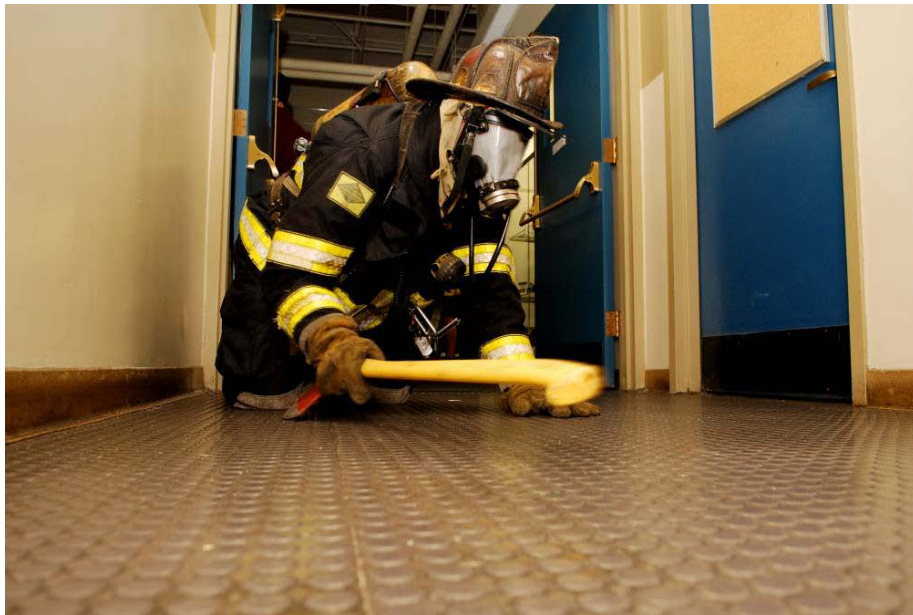
Data from FMI "shirt" and WPI pulse-oximeter

Display of floor location acts as floor display selector



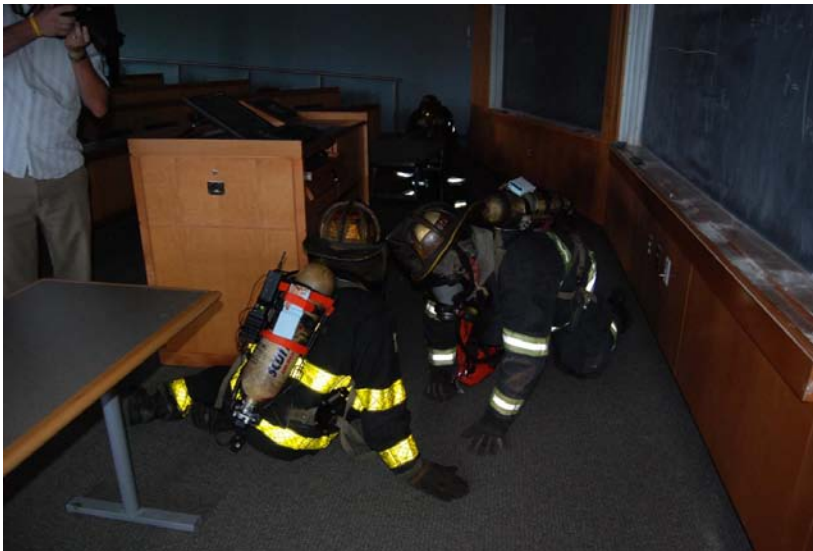
# Search Team

- Search team, tied by safety rope, crawled low, as they would in a smoke and heat filled environment.
- Face pieces are masked to simulate low visibility.
- Search path was approximately 175', with many turns and a long stairway to the second floor.



# WPI PPL Outcome

- The Rescue Team Leader guided by information from WPI PPL to victim by IC
- Victim rescued while he still had  $\frac{3}{4}$  of a bottle of air left.



# Homing System Tests

---

- Three “homing” type systems were tested
  - Handheld devices that indicate direction and relative distance to the victim and are stand-alone systems used by the search team to home in on the victim
- Technologies included:
  - Summit Safety Systems: Ultrasonic direction and range finding
  - WPI: VLF direction and range finding
  - Draeger: LF range finding

# Homing based search and rescue

---

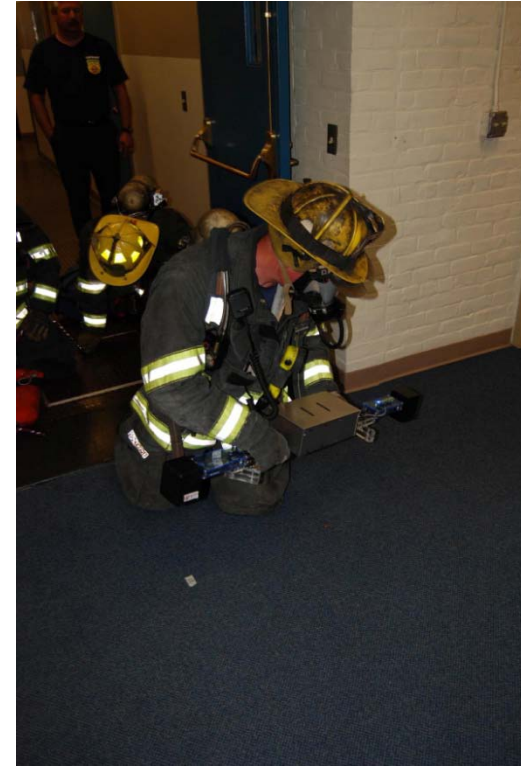
- Primary search function now falls to the Rescue team leader, with the incident commander playing an overseeing role with only radio communications to the search team.
- Some of the homing devices can provide useful information from outside the building with a perimeter search
  - Indicates closest point data as well as a general floor location.





# Homing assessment

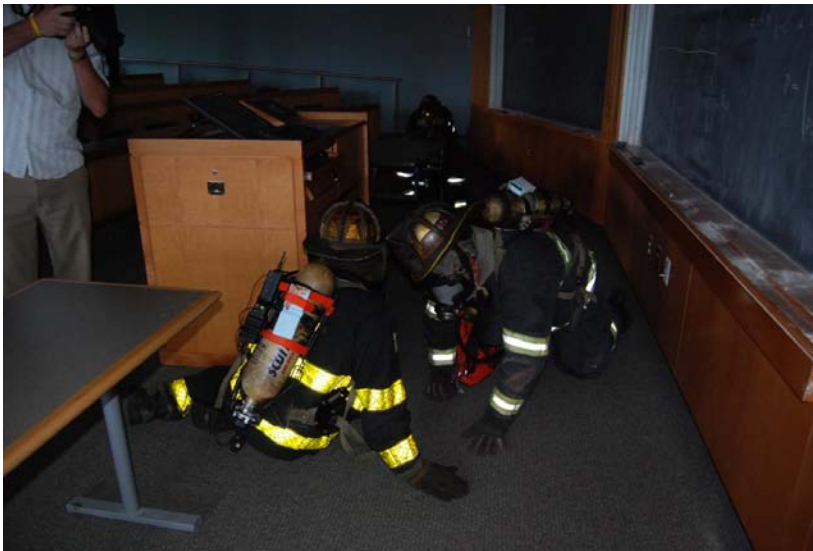
- Each homing device tested had a different set of advantages and disadvantages



- Same search/rescue scenario used as for PPL tracking systems

# WPI Mantenna Outcome

- Outdoor scan correctly identified victim's floor and general location within building
- RIT leader picked up signal near stairwell on first floor and led directly to victim



# Outcome Review

- After each test run, firefighters, fire officers, technologists and other reviewers met “off line” to gather feedback, both written and verbal.
- The firefighters described performance and ease of use of the systems and made suggestions for improvements

Written summary of results were provided to each system developer



# Overall Assessment

---

- All participants: fire service personnel, technologists and observers from many areas, including the Department of Homeland Security, deemed the “First Annual” Demo Day a great success.
- Deemed a useful demonstration of the new technologies, under tough, simulated fire service conditions, in a tough building.
- These technologies were shown to be of potentially great future value to the fire service community
  - **Homing devices are either near term or in fact available products, offering a useful interim solution sooner than locator systems will be available.**

# Update on WPI PPL Development

---

- Successful in last year's demo
  - But not yet practical/deployable
- General deployment limitations
  - Antennas on three to four sides of building
  - Cables from all antennas to central base
  - Positions of antennas pre-measured
  - Building scale operation only – not ready for LE
- This year's efforts:
  - Eliminate these limitations

# Complete Hardware Re-design

---

- The custom SDR node system and locator unit re-designed and re-implemented
  - Directly supports Geometric Auto Calibration of antenna positions
  - Hardware support for wireless nodes
  - Higher power transmitters for long distance applications
  - Streaming data acquisition to support vehicle and robot tracking

# Wireless node stations

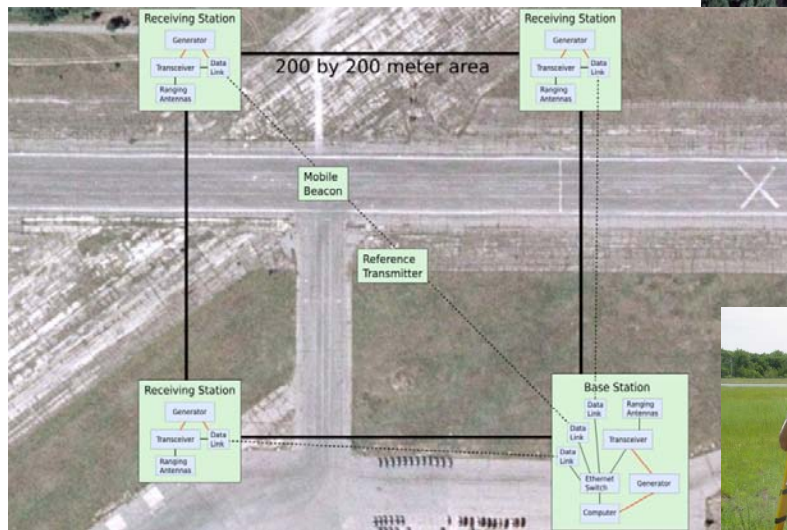
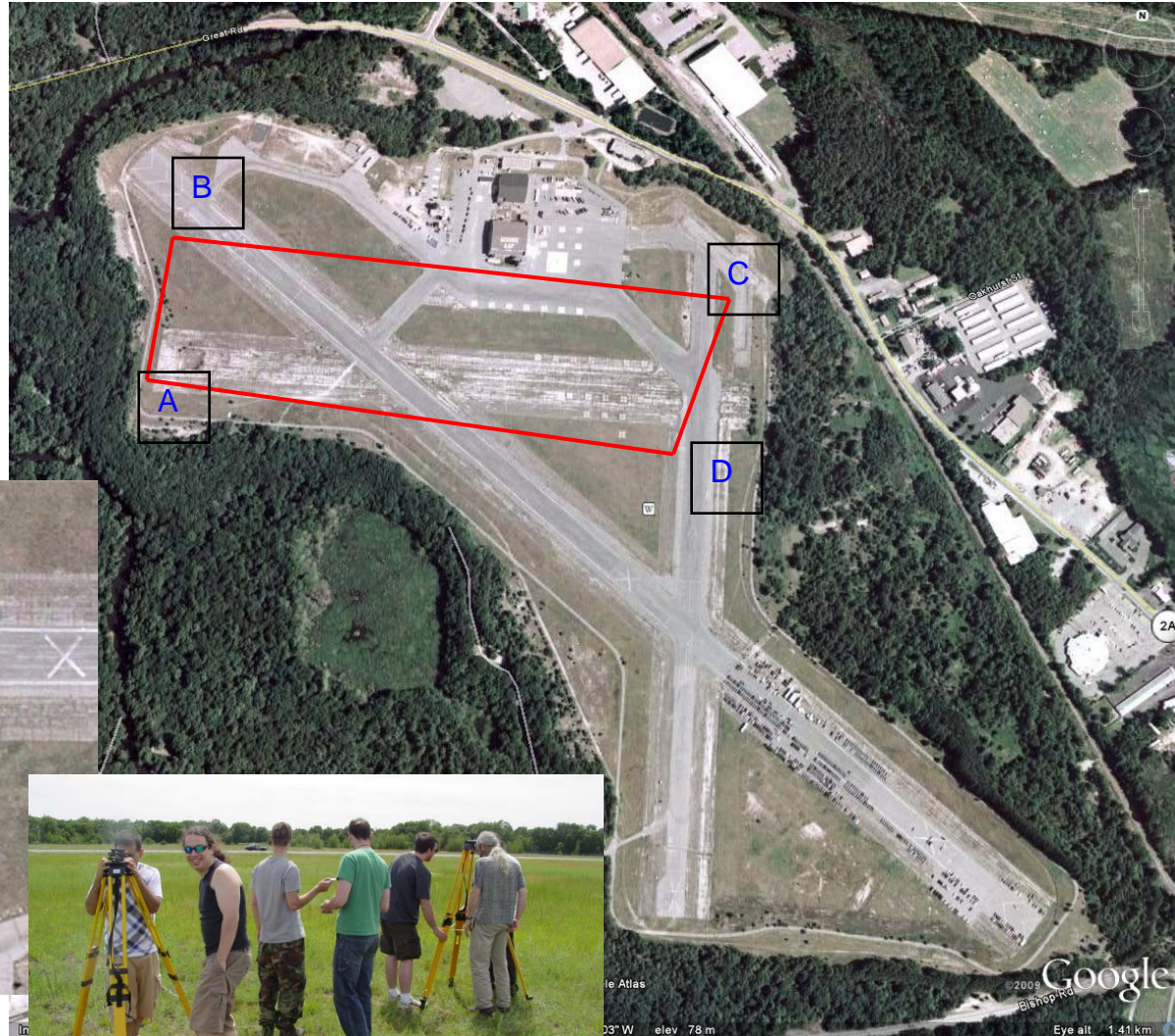
---

- WPI PPL node hardware re-designed and re-implemented to allow wireless operation
- Each node powered by an uninterruptible power unit
- Partially processed data transmitted to base station
- Eliminates all cables between antenna nodes



# Distance Test location: Devens Airfield

- Up to 1km x 200m tests conducted
- Sub-meter accuracy
- Moving vehicles tracked

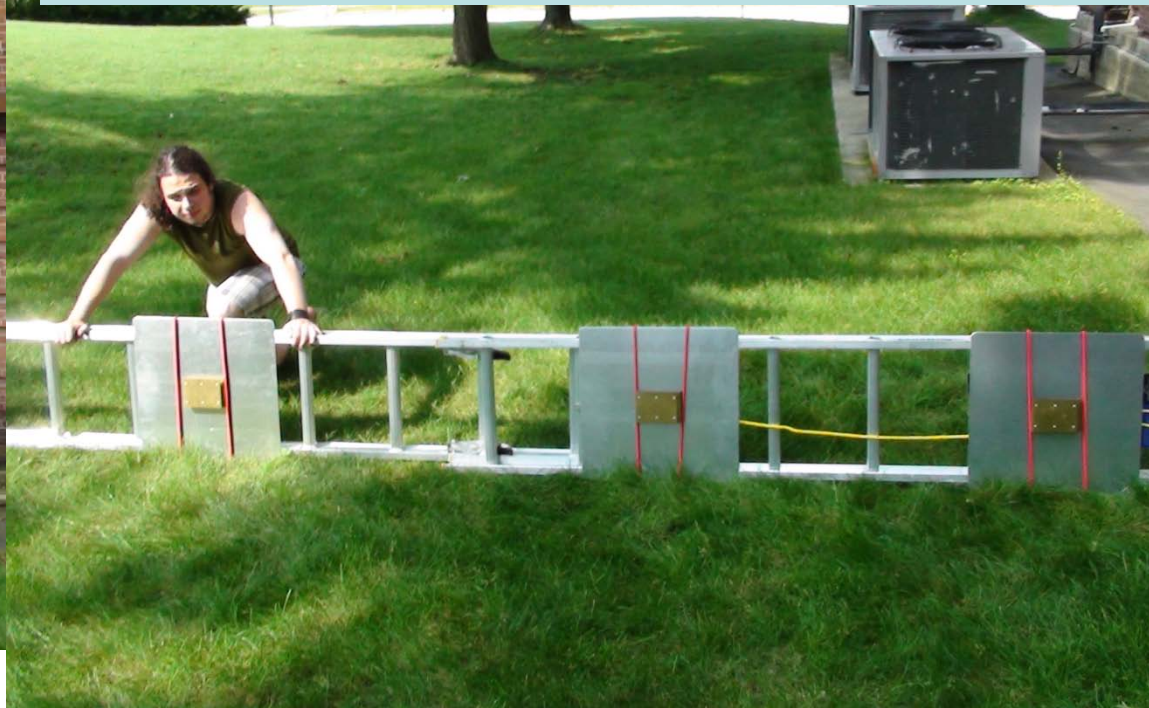




# Rapid Deployment Antennas



- Prototype uses patch antennas on extension ladders
- Coming: lightweight poles



# Low Profile Building Coverage

---

- Two “ladders” for three floor residence
- Trades depth resolution for height resolution
- “Same side” approach supports GAC



# Thank you

---

- We acknowledge the support off:
  - The rest of the WPI Research Team
  - The support of NIJ, DHS, and FEMA
- Special thanks to the 2008 Demo Day participants
  - Rex Systems Inc./ENSCO,
  - Summit Safety Systems
  - Draeger.
- Greatest thanks must go to Worcester Fire Chief Dio, his Chief Officers, Line Officers and all the fire fighters for their complete dedication to the success of the exercise.
- Thank you!
  - David Cyganski, [cyganski@wpi.edu](mailto:cyganski@wpi.edu)
  - James Duckworth, [rjduck@wpi.edu](mailto:rjduck@wpi.edu)